



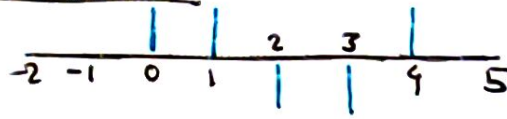
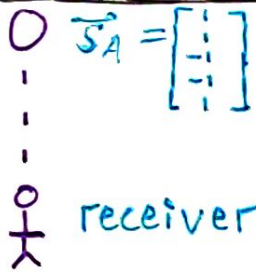
Superposition! $\vec{r} = \vec{s}_A + \vec{s}_B + \vec{n}$ noise

$$\langle \vec{r}, \vec{s}_A \rangle = \langle \vec{s}_A + \vec{s}_B + \vec{n}, \vec{s}_A \rangle = (\vec{s}_A^T + \vec{s}_B^T + \vec{n}^T) \vec{s}_A$$

$$\underbrace{\langle \vec{s}_A, \vec{s}_A \rangle}_{\text{ideally large}} + \underbrace{\langle \vec{s}_B, \vec{s}_A \rangle}_{\text{ideally small}} + \underbrace{\langle \vec{n}, \vec{s}_A \rangle}_{\text{usually small}}$$

$$\langle \vec{r}, \vec{s}_A \rangle \approx \langle \vec{s}_A, \vec{s}_A \rangle$$

ESTIMATING DELAY



$s[-1] = 0$

$s[4] = 1$

$s[0] = 1$

$s[5] = 0$

$s[n]$ is called signal

$r[0] = 0$

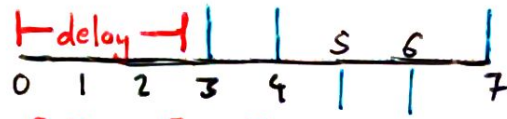
$r[7] = 1$

$r[3] = 1$

$r[8] = 0$

$\hookrightarrow s[0]$

$\hookrightarrow s[4]$



$r[n] = s[n-3]$

CORRELATION

DEF $\text{corr}_r(s_A)(k) = \sum_{-\infty}^{\infty} r[i] s_A[i-k]$

ex. $\text{corr}_r(s_A)(0) = \sum_{-\infty}^{\infty} r[i] s_A[i] = r[3]s[3] + r[4]s[4] + r[7]s[7]$

$$= 1 \cdot 1 + 1 \cdot 1 + (-1) \cdot 0 + (-1) \cdot 0 + 1 \cdot 0$$

$$= -1 + 1 = 0$$

ex. $\text{corr}_r(s_A)(-1) = r[3]s[2] + r[4]s[3] + \dots + r[7]s[6] = -3$

ex. $\text{corr}_r(s_A)(3) = r[3]s[0] + r[4]s[1] + \dots + r[7]s[4] = 5$